



Four-quadrant Characterization of Hydrodynamic Phenomena in a Low Specific Speed Centrifugal Pump*

Caracterización en cuatro-cuadrantes de fenómenos hidrodinámicos en una bomba centrífuga de baja velocidad específica

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Abstract

Objective: Identify and characterize subsynchronous hydrodynamics phenomena in a low specific speed centrifugal pump based on its four-quadrant characteristic curve. **Materials:** A 1.5 HP ITT Goulds pump instrumented with pressure transducers, an accelerometer, a torque sensor and a tachometer. Flow rate measurement was done with an ultrasonic transit time clamp-on flow meter. **Methods:** Time and frequency domain analysis with phase analysis were used to identify spectral components linked to hydrodynamic phenomena such as rotating stall and surge. **Results and discussion:** This work approaches an alternative method to calculate the phase angle using pressure signals without filtering. Related with hydrodynamic phenomena, the evidence collected suggests the presence of rotating stall in some operation points of the four-quadrant characteristic curve. Furthermore, in the third quadrant, rotating stall coexist with surge. **Conclusions:** The instrumentation and methods regarded in this work allow to collect evidence to identify in-phase and out of phase subsynchronous hydrodynamic phenomena. The classic cross-correlation-based method was improved to ease the diagnosis of subsynchronous phenomena by visual inspection. A new quantitative approach was introduced to detect subsynchronous phenomena, based on the Fourier analysis; it was validated with a case study for which the classical method was not suitable.

Keywords: Phase analysis, spectral analysis, subsynchronous phenomena, surge, rotating stall

Resumen

Objetivo: identificar y caracterizar fenómenos hidrodinámicos subsincrónicos en una bomba centrífuga de baja velocidad específica, tomando como referencia su curva característica de cuatro cuadrantes. **Materiales:** la bomba objeto de estudio se trató de una ITT Goulds de 1,5 HP, la cual fue instrumentada con sensores de presión, un acelerómetro, un sensor de torque y un tacómetro. La medición de flujo se hizo con un medidor de flujo ultrasonido. **Métodos:** análisis en el dominio del tiempo y de la frecuencia, en conjunto con análisis de fase, fueron usados para caracterizar componentes espectrales asociados a fenómenos hidrodinámicos como el *rotating stall* y el *surge*. **Resultados y discusión:** en esta investigación se propuso un método alternativo para el análisis de fase utilizando las señales de presión sin filtrar. En lo relacionado con los fenómenos hidrodinámicos, la evidencia recogida sugiere la existencia de *rotating stall* en varios puntos de la curva de cuatro cuadrantes, y, en el tercer cuadrante, la coexistencia de *rotating stall* y *surge*. **Conclusiones:** los resultados del método propuesto para el análisis de fase fueron coherentes con los del método basado en la correlación cruzada. La instrumentación y los métodos considerados en la investigación permitieron recoger evidencias para la identificación de algunos fenómenos subsincrónicos.

Palabras clave: análisis de fase, análisis espectral, fenómenos subsincrónicos, *surge*, *rotating stall*

Introduction

Centrifugal pumps are reversible machines that, depending on the direction of rotation of the impeller, can operate as pumps or as turbines. In the latter condition, the pumps are called Pumps working as Turbines or PaTs. PaTs are versatile turbomachines that can have many fields of application, among which the following can be mentioned: electricity generation in aqueduct distribution networks [1] and irrigation systems [2], replacement of pressure regulating valves [3], reverse osmosis processes and replacement of throttling devices in industrial systems [4] and energy storage in microscale [5]. The characterization of a pump with the four-quadrant curve makes it possible to know the behavior of the turbomachine in all its operating modes and to identify those operation zones where hydrodynamic phenomena may occur.

Hydrodynamic phenomena such as Rotating Stall (RS) can affect the turbomachines performance in terms of efficiency reduction, presence of high-pressure pulses and raising vibrations level [6]. Even though the RS inception has not been fully understood [7], [8], the phenomenon shows two characteristics widely mentioned in the scientific literature. First, it appears at off-design conditions, and second, it is a subsynchronous phenomenon [6], [8]–[11].

RS identification has been associated with discontinuities or slope changes in the turbomachines characteristics curves [6], [8]–[13] and has been associated with hysteresis. Flow recirculation in a centrifugal pump impeller [14] was related to hysteresis in its characteristic curve at low flow operation zone. In this case, hysteresis measurement was used to estimate efficiency losses in the studied pump.

On the other hand, the characterization of the RS (understood as its location within the turbomachine, its displacement within it and the determination of its rotation cells number) has been mainly performed with spectral analysis and phase analysis of signals obtained from pressure sensors [6], [9], [10] conveniently placed on the impeller and/or on the volute. Alternative methods considering speed signals acquisition such as LDV [8], [12], or non-intrusive methods with accelerometers [11], have also been used for the identification of the phenomenon. Computational techniques such as CFD are being widely used in the characterization of this phenomenon in turbomachines [10], [15]–[17].

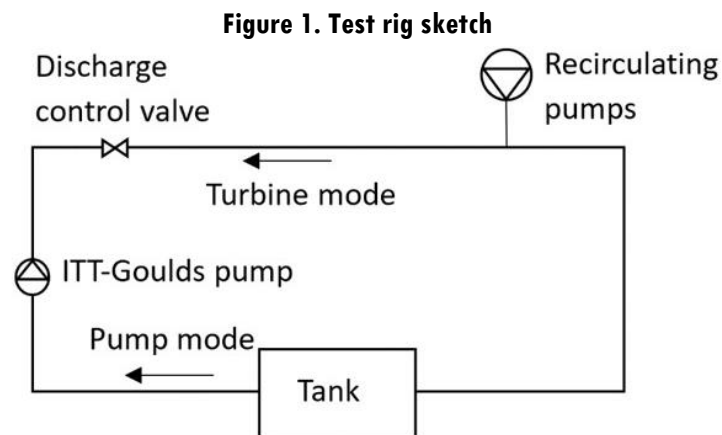
Under laboratory conditions it has been possible to characterize the RS [6], [9], [10] and, sometimes, to see it [9], [11]. However, in many cases, visualization is not possible and the external cues of hydraulic machines, such as noise and vibration, are not enough to clearly identify it. Hence, the use of techniques or methods for their identification and characterization are utmost important. Thus, the main objective of this investigation was the

identification and characterization of the RS in a specific low-speed centrifugal pump, considering its four-quadrant characteristic curve. Among the techniques used to characterize the RS, the following can be mentioned: dimensionless characteristic curves, spectral analysis [6], [9]–[11] and phase analysis [6], [10]. These techniques were used to achieve an approximation to the characterization of the phenomenon. Although the phenomenon of interest is RS, the techniques proposed to its characterization may give clues to identify other phenomena at subsynchronous level. Among these phenomena one can mention the vortex rope, fluid-induced rotordynamic forces, surge and auto-oscillation. Each of them needs additional techniques for clear identification, which are beyond the scope of this study. Nevertheless, the present investigation establishes the possibility of the existence of these phenomena in the turbomachine of interest.

Materials and Methods

Test Rig

The test rig is part of the hydraulics laboratory of Eafit University and consists of a closed circuit of pipes connected to a tank and a channel. The energy to move the water within the hydraulic system is supplied by recirculating pumps. The direction in which the flow is addressed inside the loop makes it possible to simulate the conditions of the hydraulic head, either to operate a turbomachine as a pump or as a turbine. A simplified sketch of the test rig is shown in figure 1.



Source: Own elaboration

Pump under study was an ITT-Goulds Pump of 1.5 HP and manufactured in 316 stainless steel. Its main technical specifications are displayed in table 1. The pump was operated in a

frequency range from 380 to 1751 rpm in pump mode and from 351 to 1902 rpm in turbine mode. Different rotation speeds were imposed with a frequency driver.

Instrumentation

Instrumentation used to perform the tests was as follows:

- [1] Wika A-10 piezoresistive pressure transducers in the high- and low-pressure zones.
- [2] Dytran 2005V piezoelectric pressure transducer in the volute.
- [3] Futek PMP300 piezoresistive pressure transducer in the volute, placed 30 degrees from the Dytran 2005V piezoelectric pressure transducer.
- [4] Kistler 8704B50M1 accelerometer installed on the volute.
- [5] Futek TRS600 FSH01998 torque sensor placed on the pump shaft.
- [6] General Electric (GE) TransPort PT878 ultrasonic flow meter mounted on the 6-inch pipe in the high-pressure zone.
- [7] An optical sensor (DT2234C+) was mounted pointing towards the shaft of the machine. A reflective mark on the shaft served as the key phasor.

From now on, the sensors mounted on the volute will be called as follows: The Dytran 2005V as PES (Piezo Electric Sensor), the Futek PMP300 as PRS (Piezo Resistive Sensor) and the Kistler 8704B50M1 as accelerometer. Figure 2 shows the location of the measuring instruments and figure 3 the polar location of PRS and PES.

Table 1. ITT-Goulds Pump technical specifications

| Impeller | |
|------------------------------------|-------------------------|
| External diameter | 0.14764 m |
| Reference diameter | 0.08104 m |
| Number of blades (backswept) | 6 |
| Inlet/outlet | |
| Inlet diameter (suction nozzle) | 0.0635 m |
| Outlet diameter (discharge nozzle) | 0.0508 m |
| Design conditions | |
| Specific speed (Ns) | 35.7 |
| Rotation speed | 29.167 s ⁻¹ |
| Discharge | 0.009 m ³ /s |
| Head | 7.7 m |
| Power | 1118.5 Watts |

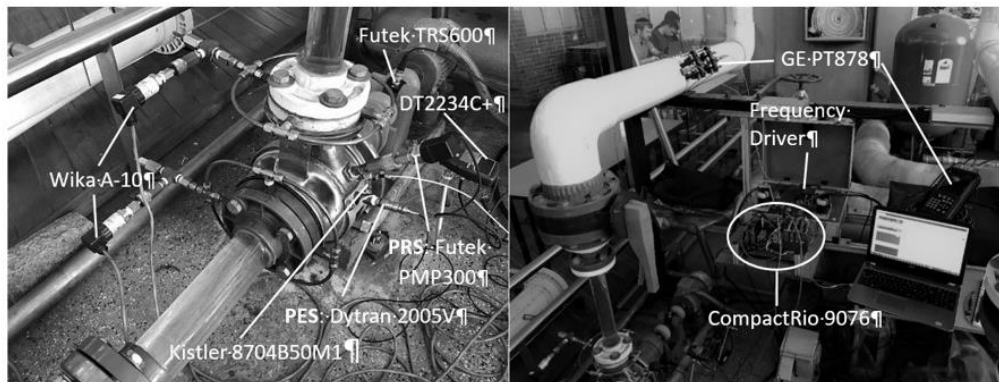
Source: Own elaboration

Data Acquisition Equipment

Electrical signals transmitted by the sensors were received and processed by a National Instruments® CompactRio® 9076 Data Acquisition Equipment (DAE) and a software called Turbologger, developed in a LabView® environment by researchers from EAFIT University. The DAE was configured with four acquisition modules: Two NI-9232, one NI-9215 and one NI-9203. General technical specifications of the modules are shown in [18].

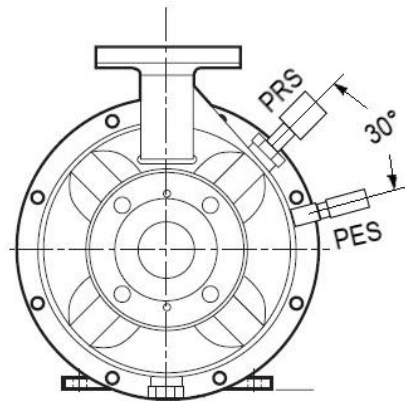
All signals were logged simultaneously and composed of 655360 data for each one of the variables at each operation point (OP). Operation points (OPs) were obtained by varying the impeller rotational speed and the flow rate. Between consecutive OPs the speed varied among 1 and 20 rpm and the flow rate among 0.1 and 0.2 l/s. Sampling rate was 20480 Hz. Acquired signals were used to observe harmonic phenomena within the alias-free band ranging from 0.03 Hz (fundamental Fourier frequency) and 10240 Hz (Nyquist frequency). Current and voltage signals were converted to engineering units of the International System of Units (SI).

Figure 2. Location of the instruments used in the measurements



Source: Own elaboration

Figure 3. Polar location of PRS and PES



Source: Adapted from ITT Goulds Pumps [19]

Characteristic Curves

A convenient way to characterize all operation modes of a centrifugal pump is through the four-quadrant curve proposed by Knapp in 1937, which relates rotation speed and discharge [20]. The four-quadrant curve used in this investigation differs from Knapp's in the use of dimensionless numbers, velocity and discharge factors, n_{ED} and Q_{ED} respectively, defined as established by IEC-60193 [13]. In addition to this, characteristic curves of velocity (n_{ED}) vs. torque (T_{ED}) factors, velocity (n_{ED}) vs. power (P_{ED}) factors and energy (E_{nD}) vs. flow (Q_{nD}) coefficients were made. Dimensionless factors and coefficients were also estimated according to the same standard. Factors and coefficients definitions involved in the characteristic curves are presented in equations (1)–(6).

$$n_{ED} = \frac{nD}{E^{0.5}} \quad (1)$$

$$Q_{ED} = \frac{Q}{D^2 E^{0.5}} \quad (2)$$

$$T_{ED} = \frac{T}{\rho D^3 E} \quad (3)$$

$$P_{ED} = \frac{P}{\rho D^2 E^{1.5}} \quad (4)$$

$$E_{nD} = \frac{E}{n^2 D^2} \quad (5)$$

$$Q_{nD} = \frac{Q}{nD^3} \quad (6)$$

Where, n is rotational velocity (s^{-1}), D is reference diameter (m), Q is discharge (m^3/s), E is specific energy (Nm/kg), T is torque (Nm), ρ is density (kg/m^3) and P stands for the power (Nm/s).

The characteristic curves were built with 335 points located in all possible modes of operation of the turbomachine under study.

Spectral Analysis

Spectral analysis was performed on the signals from pressure sensors installed in the volute (PES and PRS) and for all OPs considered in the characteristic curves. The pressure signals were converted to their corresponding pressure fluctuation coefficients, \tilde{P}_E , defined by equation (7), according to IEC-60193 [13].

$$\tilde{P}_E = \frac{p - \bar{p}}{\rho E} \quad (7)$$

Where, p is pressure (N/m²) and \bar{p} is the average pressure (N/m²)

Frequencies were also represented as dimensionless coefficient, f_n , defined by equation (8), agreeing with the standard IEC-60193 [13].

$$f_n = \frac{f}{n} \quad (8)$$

Spectral analysis was based on the Fast Fourier Transform of pressure signals. Frequency band from 0 to 2.5 times the rotation speed of the machine was regarded; i.e., $0 \leq f_n \leq 2.5$. The spectral components clearly identified by the two sensors in the volute at the same frequency were taken under consideration. From this information, spectral behavior patterns were determined for each quadrant in the Q_{ED-NED} characteristic. Procedure details carried out can be found in [21].

Phase Analysis

The wave number, k , is estimated from the phase analysis. k is useful for determining the number of rotating cells and rotation speed in the case of Rotating Stall [10]. However, this estimate might be ambiguous since the frequency of passage of the phenomenon (f_{pg}) perceived by a sensor is either the effect of the passage of one cell rotating at high speed or the effect of several cells rotating at low speeds [22]. This ambiguity can be resolved with the graph of the cross-correlation of the pressure signals, previously filtered, as proposed by Best, LaFlamme and Moffatt [22], and Fortin and Moffat [23]. The proposal of these authors consists of identifying pairs of consecutive peaks with the greatest correlations, which represent the period mark of the hydrodynamic phenomenon. Then, counting the oscillations between these peaks corresponds to k . Nevertheless, the application of the method is not always suitable because the result of cross-correlation of filtered signals does not clearly show the peaks representing the period mark of the phenomenon and counting fluctuations between them becomes a subjective task. In order to overcome this problem, the following relationship was proposed between the phase angle estimated by the Fourier coefficients on

the original signals, i.e. unfiltered signals, and the polar angle separating the two sensors on the volute. This is referred as the k -Fourier-coefficients method.

$$k_{\theta} = \frac{\Delta\theta}{\theta_G} \quad (9)$$

Where,

k_{θ} : Wave number estimated by the k -Fourier-coefficients method,

$\Delta\theta$: Phase-shift angle estimated by Fourier-coefficients, and

θ_G : Polar angle separating the sensors on the volute.

Deduction of equation (9) is shown in [21]. It was assumed that cells rotate at a constant speed and if several cells are present, they are equidistant.

To validate the k -Fourier-coefficients method, k was also estimated by filtering the signals and then calculating the cross-correlation of the signals. In this validation the pressure signals were filtered with digital bandpass filters that were chosen in such a way that they did not significantly affect the response of the signals in phase or amplitude. The filters regarded were Elliptic, Butterworth, Chebyshev type 1 and type 2 and Kaiser. The validation can be seen in [21].

For the analysis of rotating cells, k was adjusted according to the following hypotheses: First, the wave number is an integer number of stall cells that occupies the circular domain. Second, the passage frequency perceived by the sensors (f_{pg}) is equal to the wave number by the frequency of the phenomenon (f), w.r.t. an inertial frame of reference [22]. Third, in order to fulfill the above hypothesis, it is necessary to correct the value of the frequency of the phenomenon (f) to guarantee that:

$$f_{pg} = k f \quad (10)$$

In terms of frequency coefficients, equation (10) is written as:

$$f_{n.pg} = \frac{f_{pg}}{n} = k f_n \quad (11)$$

Phase analysis was performed for some components identified in the spectral analysis at operating points such as best efficiency, minimum torque, change of slope sign on the Q_{ED} - n_{ED} characteristic and those representing significant variations in pressure fluctuation.

Subsynchronous Phenomena

Rotating Stall: It can be defined as a flow disturbance in a turbomachine resulting from backflows that partially or totally block the channels between the rotor blades. The backflows are associated with flow shedding at the solid-fluid interphase due to alterations in the angle of attack of the flow when it enters the channels between the blades. In turbines it is common to find RS at frequencies from 0.5 to 0.7 times the rotation frequency of the rotor [24]. In pumps, RS can be found at frequencies between 0.05 and 0.10 times the rotation frequency of the rotor [8, 28].

Surge and auto-oscillation: Surge is a disturbance involving all components of a hydraulic system, which causes pressure and flow rate fluctuations throughout the system. When this type of disturbance is associated with cavitation it is called auto-oscillation [24]. The literature reviewed does not point out the typical frequencies of the surge in hydraulic turbomachines.

Vortex rope: This phenomenon is generated in the draft tube of turbines and consists of a swirl with a low-pressure core where cavitation occurs. The vortex core has a helical shape with a precession frequency of 0.25 to 0.35 times the rotation frequency of the rotor [25]. In the case of PaT's, it can be seen in the low-pressure pipe since it works as a draft tube.

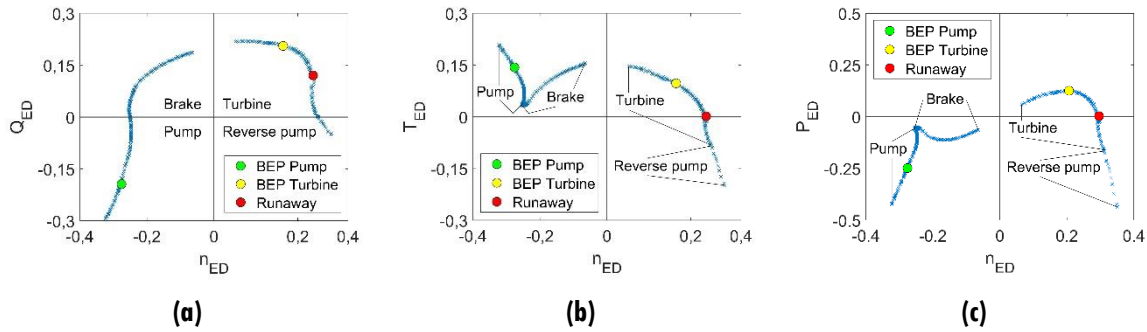
Fluid-induced rotordynamic forces: This phenomenon occurs when the rotation axis of the rotor-shaft system is slightly displaced from its mid-position by effects of the fluid. The rotodynamic forces will be a function of the frequency of the rotor, but not of the displacement [26]. It is common that this phenomenon appears at subsynchronous frequency [24].

Results

Characteristic Curves

Figure 4 depicts characteristic curves Q_{ED-NED} (figure 4a), T_{ED-NED} (figure 4b) and P_{ED-NED} (figure 4c). Table 2 presents the values of speed factor, flow factor, torque factor and power factor for the Best Efficiency Point (BEP) in pump mode, the BEP in turbine mode and the runaway.

Figure 4. Characteristic curves of the pump under study



Source: Own elaboration

$Q_{ED}-n_{ED}$ characteristic is properly called the four-quadrant curve, which are pointed out in figure 4a. The first quadrant corresponds to a pump, the second to a brake, the third to a turbine and the fourth to a reverse pump. The runaway point splits the third quadrant into two regions: turbine and brake turbine. [13]. In the case of the $T_{ED}-n_{ED}$ and $P_{ED}-n_{ED}$ curves, their quadrants do not correspond directly to the quadrants of the $Q_{ED}-n_{ED}$ characteristic (see figures 4b and 4c).

Table 2. Speed, flow, torque and power factors of the relevant points of the characteristic curves

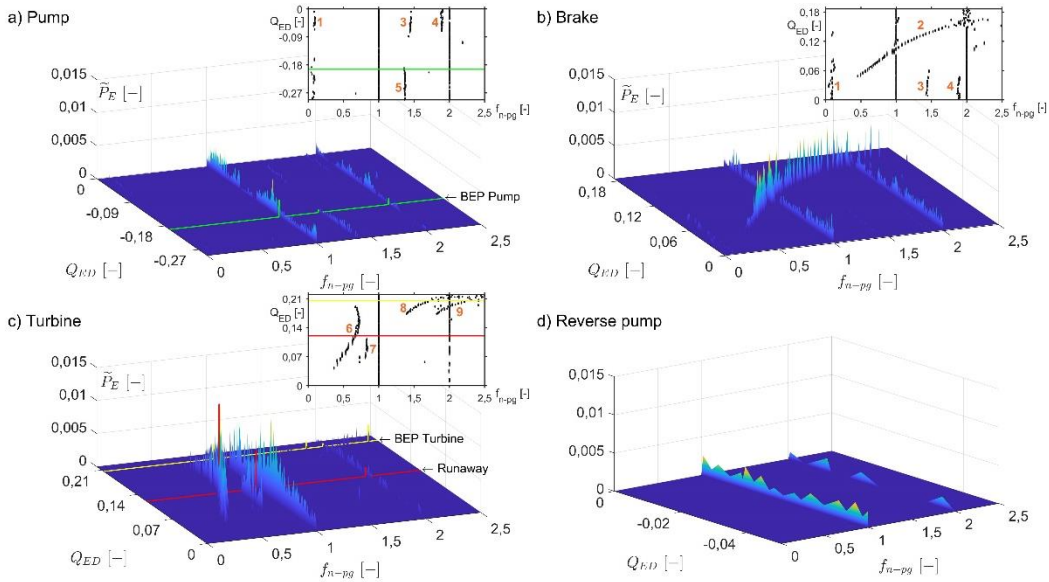
| OP | n_{ED} | Q_{ED} | T_{ED} | P_{ED} | Observation |
|-------------|----------|----------|----------|----------|--------------------------|
| BEP Pump | -0.2759 | -0.1939 | 0.1432 | -0.2482 | $\eta = 78.1 \%$ |
| BEP Turbine | 0.2063 | 0.2056 | 0.0970 | 0.1258 | $\eta = 61.2 \%$ |
| Runaway | 0.2959 | 0.1202 | 0.0017 | 0.0031 | $T \approx 0$ (0.04 N.m) |

Source: Own elaboration

Spectral Analysis

Figure 5 illustrates spectral patterns as a function of frequency and flow coefficients for the PES signals in the band $0 \leq f_n \leq 2.5$. The spectra of the BEP in pump mode, BEP in turbine mode and runaway were highlighted. In quadrants 1, 2 and 3 a 2D representations Q_{ED} vs f_n are added too. Since only matching spectra were taken from the PES and PRS sensors, it is not necessary to display the PRS graph. Spectral components of the PES and PRS signals only differ in amplitude. The amplitude of the spectral components obtained by PRS signals was greater than that of the PES signals in most cases.

Figure 5. Spectral patterns in the QED-nED characteristic curve obtained from PES signals



Source: Own elaboration

Spectral components 1X and 2X are present in all operation modes, albeit they are not evenly distributed along the whole range of flow coefficients. Component 1X represents the shaft frequency and 2X emerges from non-sinusoidal excitations at the shaft frequency [24]. Description of the other spectral patterns is shown in table 3.

Table 3. Description of the spectral patterns

| Pattern | Location | Remarks |
|---------|---|--|
| 1 | $0.07 \leq f_n \leq 0.11$ $-0.0646 \leq Q_{ED} \leq 0.0782$ | It extends from quadrant 1 to quadrant 2 in the border area. Low variability of f_n around 0.09. |
| 2 | $0.47 \leq f_n \leq 2.23$ $0.0522 \leq Q_{ED} \leq 0.1646$ | Pattern in the brake quadrant. Very high variation of f_n . |
| 3 | $1.42 \leq f_n \leq 1.47$ $-0.0881 \leq Q_{ED} \leq 0.0587$ | It extends from quadrant 1 to quadrant 2 in the border area. Low variability of f_n around 1.45. |
| 4 | $1.86 \leq f_n \leq 1.91$ $-0.0707 \leq Q_{ED} \leq 0.0477$ | It extends from quadrant 1 to quadrant 2 in the border area. Low variability of f_n around 1.89. |
| 5 | $1.36 \leq f_n \leq 1.38$ $-0.2934 \leq Q_{ED} \leq -0.1939$ | Pattern in the low load of the pump quadrant. Low variability of f_n around 1.37. |
| 6 | $0.37 \leq f_n \leq 0.68$ $0.0397 \leq Q_{ED} \leq 0.1891$ | This pattern covers part of the turbine zone and most of the turbine-brake zone. High variation of f_n . |
| 7 | $0.81 \leq f_n \leq 0.83$ $0.0678 \leq Q_{ED} \leq 0.1114$ | Pattern in the high load of the turbine-brake zone. Low variability of f_n around 0.82. |
| 8 | $1.39 \leq f_n \leq 2.14$ $0.1746 \leq Q_{ED} \leq 0.2171$ | Pattern in turbine mode in quadrant 3. High variation of f_n . |
| 9 | $1.81 \leq f_n \leq 2.42$ $0.1731 \leq Q_{ED} \leq 0.2087$ | Pattern in turbine modo in quadrant 3. High variation of f_n . |

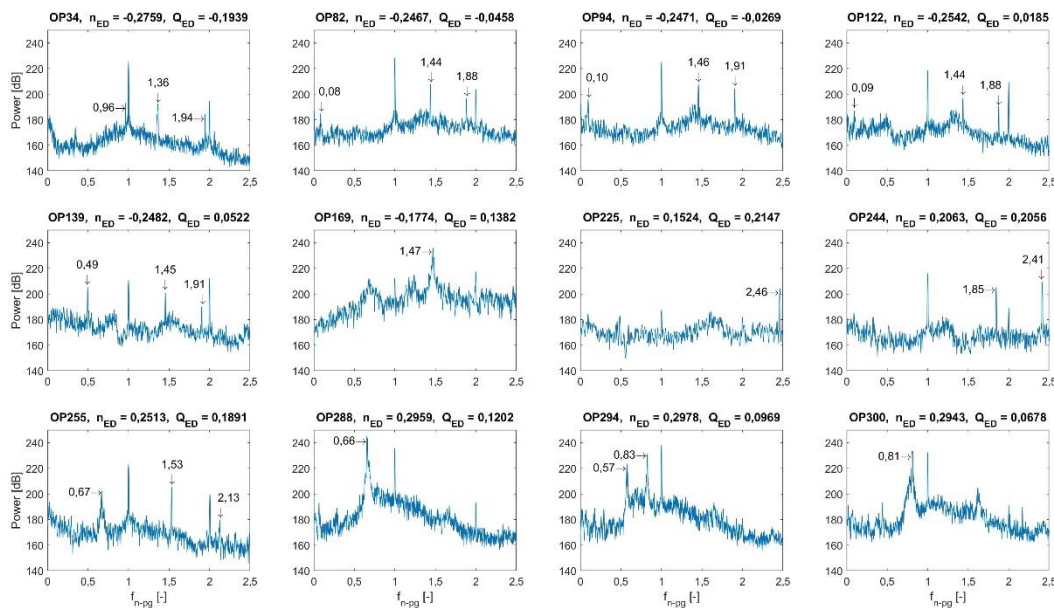
Source: Own elaboration

Phase Analysis

Phase analysis was focused on the calculation of k -number by the k -Fourier-coefficients method (k_θ) on some spectral components identified in spectral analysis. Most of these components are part of the spectral patterns depicted in figure 5.

Twelve OPs were selected from the Q_{ED} - n_{ED} characteristic curve for the phase analysis. The cross-correlation of the PES and PRS signals was computed to identify the most highly correlated spectral components for the selected OPs. Figure 6 shows the cross spectrum of the two signals with the spectral components considered in the phase analysis.

Figure 6. Cross-spectra of PES and PRS signals



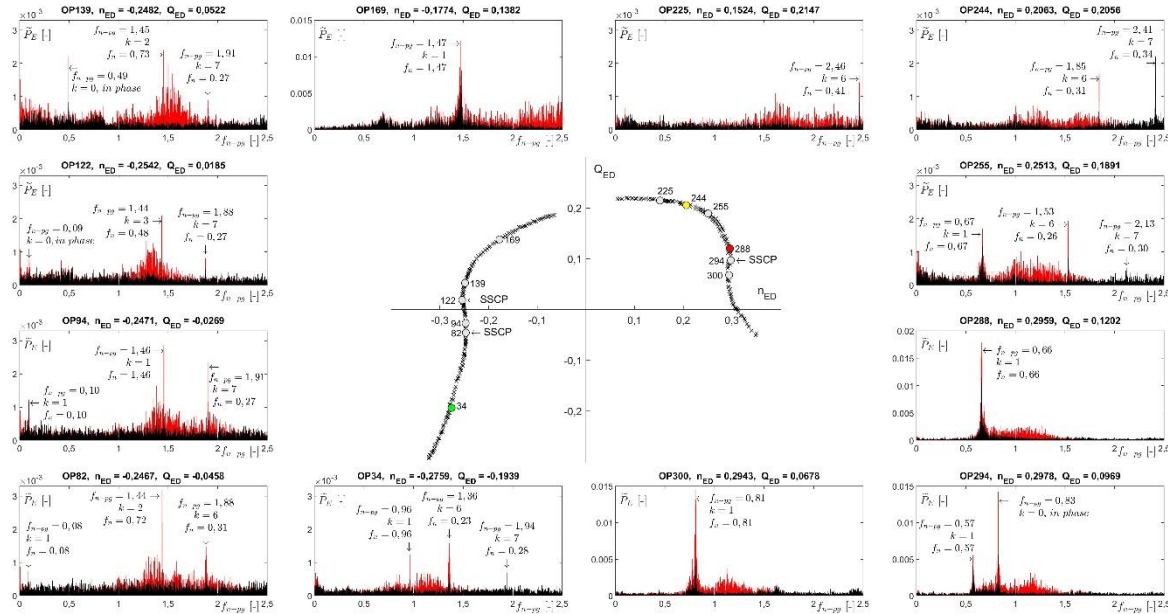
Source: Own elaboration

A chart depicting the spectra of 12 representative OPs on the Q_{ED} - n_{ED} characteristic curve is given in figure 7. It highlights the matching spectral components of PES (black spectra) and PRS (red spectra) and it shows each component of interest with its frequency detected by the sensors (f_{n-pg}), its k -number and the frequency of the hydrodynamic phenomenon (f_n). Spectral components $f_n = 1$ and $f_n = 2$ are not shown in the graph. Figures 8a and 8b display the location of the same 12 OP in the T_{ED} - n_{ED} and P_{ED} - n_{ED} characteristics, respectively.

The discrepancies between the spectra of the two sensors mounted on the volute (see figure 7) are given by the type of sensor. The PRS is a sensor used mainly for industrial process control and measures total pressure values, while the PES is a highly sensitive sensor used to measure pressure variations with respect to the average (pressure fluctuations). While the

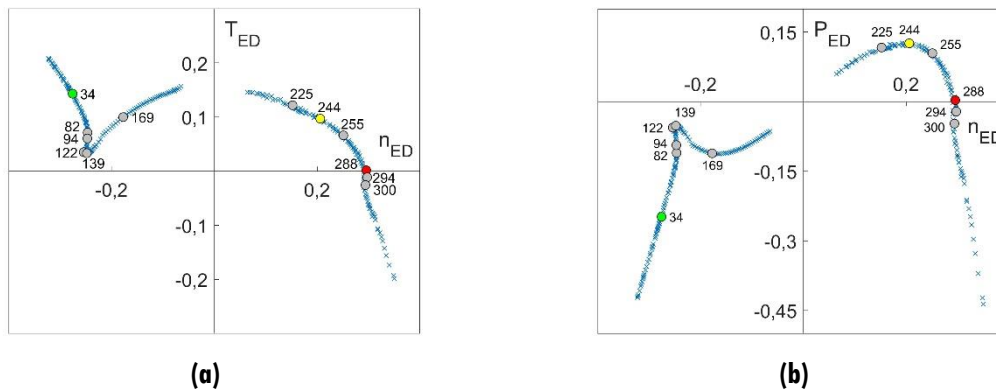
PRS can measure phenomena with frequencies up to 250 Hz, the PES can measure dynamic phenomena up to 40 KHz. Although the two sensors are very different, it is important to mention that the frequency range considered in this investigation was from 1 to 79.25 Hz, which is within the span of the two sensors.

Figure 7. Q_{ED} - n_{ED} characteristic curve and some representative operating points with their corresponding amplitude spectra



Source: Own elaboration

Figure 8. T_{ED} - n_{ED} and P_{ED} - n_{ED} characteristics with 12 operating points highlighted



Source: Own elaboration

It is important to notice that in the time domain the relationship between f_n and k -number can be seen using correlation of the filtered signals [22], [23]. Figure 9 shows an example of the correlation between the PES and PRS signals for a spectral component $f_n = 1.85$ in OP244 (BEP Turbine) with $n = 18.3452$ Hz. This graphical representation will be referred from now on *BB-Plot* (Bolaños-Botero Plot) since the contribution from the authors. The strips

represent the period of the phenomenon (T) and the number of peaks or valleys into each strip corresponds well to k . The time differential between consecutive peaks corresponds to the passage period (T_{pg}), i.e., the period perceived by the sensor. The results shown in equations (12) and (13) can be estimated from figure 9.

$$f_{pg} = \frac{1}{T_{pg}} = 33.898 \text{ Hz} \quad (12)$$

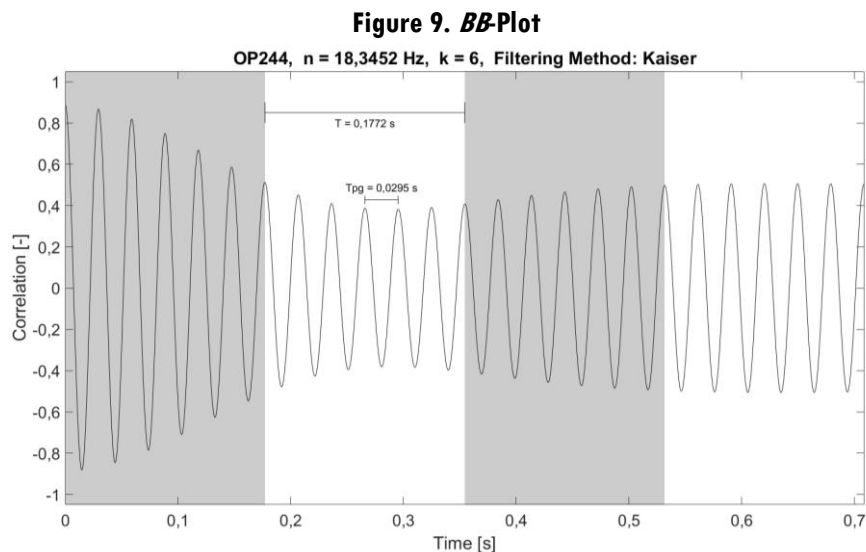
$$f_{n-pg} = \frac{f_{pg}}{n} = 1.846 \quad (13)$$

Each strip in figure 9 contains 6 peaks or valleys, which means that $k = 6$. Hence the frequency of the phenomenon can be computed by dividing equation (13) by k , yielding what is presented in equation (14).

$$f_n = \frac{f_{n-pg}}{k} = 0.308 \quad (14)$$

As expected, the passage frequency computed from the passage period estimated by the BB-Plot corresponds to the frequency identified in the spectrum of the sensors mounted in the volute (see figures 6 y 7).

The power of this approach lies in the ability to feature the period of the phenomenon that, as can be seen, is not evident in the bare graph of the cross correlation. This is a significant improvement to the graphical method proposed by Best, LaFlamme and Moffatt [22], and Fortin and Moffatt [23], which is inappropriate for this case.



Source: Own elaboration

Acceleration and Pressure Fluctuation Analysis

Pressure fluctuations and acceleration may be indicative of hydrodynamic phenomena [27]. In order to identify possible areas of operation of the turbomachine under study with the presence of this type of phenomena, the results of the spectral patterns (figure 5), the components of interest (figure 6) and the location of the OPs highlighted in the characteristic curves (figures 7 and 8) were related with the RMS curves of the PES and accelerometer versus Q_{nD} . Figure 10 shows the PES and accelerometer RMS curves and the possible operating zones (OZ) with hydrodynamic phenomena.

OZ 1

A periodic phenomenon predominates with $f_{n_{pg}} = 1.37$ and $k = 6$ in an interval of Q_{ED} between 0.1938 and 0.2934 (pattern 5 of figure 5). The frequency of the phenomenon is about 23 % of the frequency of the rotor. The evidence gathered in the laboratory and the reviewed literature do not suggest the existence of RS in this zone. In quadrant 1 RS would be expected in the zone of high heads and low flows [24], [27]. Being a phenomenon that occurred in all the OPs in the Q_{ED} range already indicated and discarding the existence of RS for the reason previously exposed, it is presumed that the spectral component is associated with rotodynamic forces induced by the fluid, which can occur at subsynchronous level [24].

OZ 2

This area corresponds to the border between quadrants 1 and 2 (patterns 1, 3 and 4 of figure 5). It starts at the SSCP in quadrant 1 (OP82) and ends at the lowest torque point in quadrant 2 (OP139). This area has spectral components around $f_n = 0.09$, some in phase (see OP122 in figure 7) and some not (see OP82 and OP94 in figure 7). According to [8], [28], the RS occurs in centrifugal pumps at frequencies of 5 to 10 % of machine rotation ($0.05 < f_n < 0.10$), which would be in accordance with the results obtained. On the other hand, according to [27], two conditions can be identified that are indicative of RS. The first is the gradual increase and decrease of the pressure pulses (bell shape) as a function of Q_{nD} ; and the second, the spectral components related to RS have similar phase-shift angles in the zone. The first condition can be seen in figure 10a. The second condition is satisfied with OP82 and OP94. However, the existence of one component in phase in the OP139 (point of minimum torque in pump mode) also suggests the existence of Surge, if it is considered that authors such as Day [7] point out that Surge and SR are related and in some cases one of the phenomena precedes the other.

The OPs with evidence of RS exhibit a wave number (k) equal to one, suggesting that if the phenomenon occurs, it would have one rotating cell.

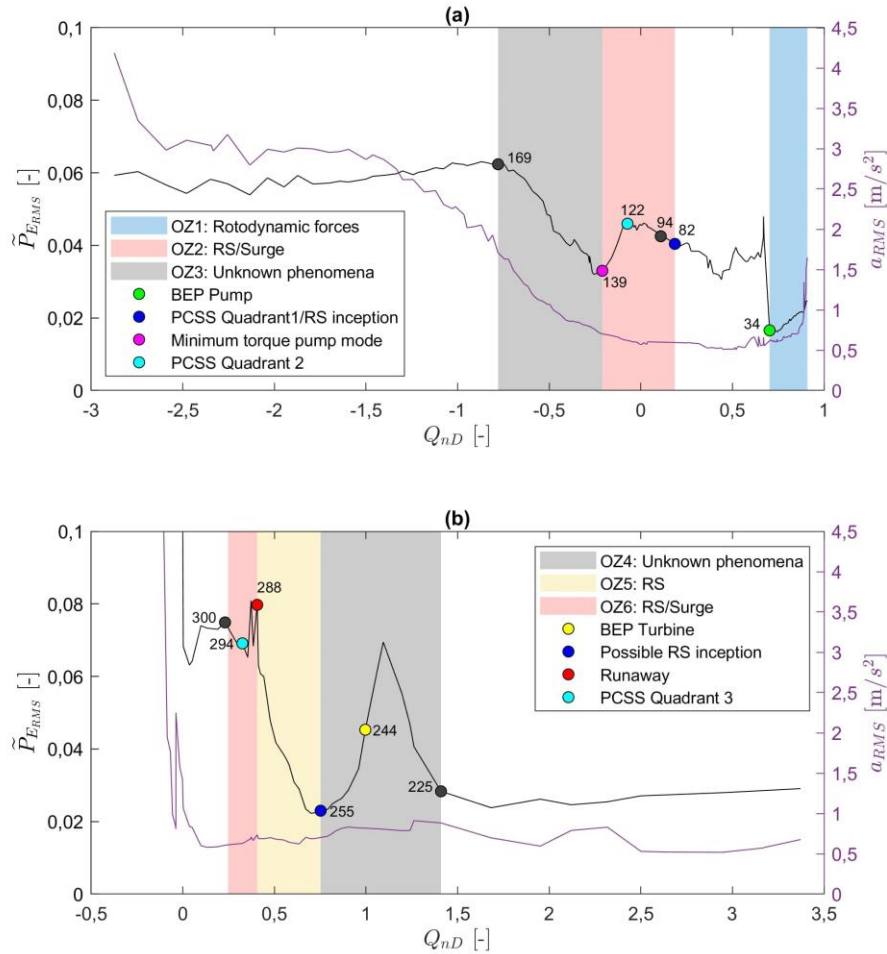
07 3

Strong vibrations are present from OP139 to the last OP in quadrant 2 (see figure 10a) with the particularity that f_{n-pg} changes as Q_{nD} increases. The evidence gathered in the laboratory and the literature reviewed does not allow to draw a conclusion about the type of hydrodynamic phenomenon that could explain this behavior, but an eventual RS is ruled out because there is no zone with onset, development and decay of the pressure fluctuations, characteristic of this phenomenon [9], [11], [27]. Figure 10a shows, on the one hand, the RMS of pressure fluctuations with a pronounced growth from OP139 to OP169, and thereafter, a very slight drop to the last operating point of the quadrant 2 (OP203). On the other hand, the RMS of the accelerometer signals shows a permanent increase from OP139 to OP203 (pattern 2 of figure 5).

07 4

Figure 10b shows an area of increases and decreases in pressure pulses in the range $0.752 \leq Q_{nD} \leq 1.409$ (between OP225 and OP255), with uniform levels of vibration. This zone is characterized by OPs with sharp spectral components ranging from $f_n = 1.8$ to $f_n = 2.45$, with k between 3 and 7, suggesting subsynchronous rotating phenomena at f_n between 0.30 and 0.71. The spectral components frequency and the shape of the zone state the existence of RS, however, the place where it is located is not usual for this phenomenon. According to the literature, RS is expected in the turbine-brake zone [9], [11], [27], [29]. As no other evidence is available, the existence of RS in this area cannot be suggested. Further investigations may elucidate this issue.

Figure 10. (a) RMS of the PES and accelerometer signals in the pump and pump-brake operating modes, and (b) RMS of the PES and accelerometer signals in the turbine, turbine-brake and reverse pump operating modes



Source: Own elaboration

OZ 5

This zone corresponds to the grey strip in figure 10b with spectral components typical of an RS (55 % to 71 % of the impeller rotation speed), with $k = 1$ and phase-shift angles between 20.5° and 24.1°, which are close to the angle of separation between the pressure sensors placed in the volute. In pump-turbines operating in turbine mode, RS rotation frequencies have been reported in around the 70 % of the impeller rotation in the runaway speed [9], or by the 59 % in the turbine-brake zone near the runaway condition [29], which would be in accordance with the results obtained. For the runaway there is a frequency of 66 % of the impeller frequency and near the runaway (OP294), in the turbine-brake zone, of 57 %.

0Z 6

This zone exhibits spectral components around $f_n = 0.82$, some of them in phase ($k = 0$) and others not ($k = 1$). This zone is represented in figure 10b as a yellow strip. The in-phase phenomenon can be described as pressure and flow oscillations involving the entire hydraulic system, thus a surge or auto-oscillatory phenomenon [27] while the non-phase one fits well with a one-cell RS. This symbiosis is not unexpected considering that the two phenomena have been intimately linked in compressors, and until the 50's of the 20th century no clear differentiation had been made between the two types of perturbations [7].

The spectrum for OP294 corresponds to the PCSS in quadrant 3 (see figure 7) and shows two components that point, on the one hand, the presence of an RS ($f_n = 0.57$ and $k = 1$), and, on the other hand, the presence of a surge ($f_n = 0.83$ and $k = 0$). According to Day [7], both types of disturbances can occur at the same point of instability in a compression system. The evidence collected suggests therefore that this might occur as well in hydraulic systems.

Additional Remarks

- [1] Quadrant four did not display spectral components of interest other than $f_n = 1$ and $f_n = 2$ (see figure 5). However, it is important to notice that the high-pressure pulses and high vibrations are experienced in this quadrant. Figure 10b was deliberately trimmed on the vertical scale to maintain the aspect ratio with figure 10a. However, from $Q_{nD} = 0$, and below, the pressure pulses increase vertiginously. In the case of the RMS of \bar{P}_E a maximum value of 3.37 was reached, and for the RMS of the acceleration a value of 9.45 m/s^2 .
- [2] The Vortex rope was observed in some OP in the lower part of the turbine mode and in the upper part of the turbine brake mode (OP 280 to OP294). However, the spectra of these points did not exhibit typical components for this phenomenon, which according to Escaler *et al* [25] are between 0.25 and 0.35 times the rotation frequency of the rotor. It is assumed that the location of the pressure sensors did not allow the detection of this phenomenon using the spectra.

Conclusions

Results allow to draw these main conclusions:

- [1] This research collected evidence to define at least three areas of interest where the occurrence of RS and/or Surge is suggested. First area, between quadrant 1 and 2 (OZ2), with components in the range $0.083 \leq f_n \leq 0.096$ some of them in-phase and others not. Second one, in the lower part of turbine mode (OZ5), prior to runaway, exhibits spectral components out-of-phase in the range $0.51 \leq f_n \leq 0.71$. Third area, in turbine-brake mode (OZ6), with spectral components in the range $0.81 \leq f_n \leq 0.84$. This area is the most controversial because the evidence exposes that in two operating points coexist simultaneously two hydrodynamic phenomena, one in phase and the other not. This type of behavior has been reported in compressors [7] but not in pumps as turbines.
- [2] The classical method proposed by Best, LaFlamme and Moffatt [22], and Fortin and Moffat [23] to identify visually the k -number is unsuitable in some conditions. This limitation was overcome with the BB-plot which is a variant to the cross-correlation method.
- [3] A quantitative method to estimate the wave number, referred to as the k -Fourier-coefficients is introduced. It is a feasible alternative to determine the wave number k , with the great advantages of not requiring time domain signal pre-processing; i.e., saving time and computational resources. The wave number allows discriminating a RS and corresponds, at the same time, to the number of stall rotating cells.
- [4] The spectral pattern observed in quadrant two (pattern 2), where the frequency coefficient increases as the flow coefficient increases, can become a line of investigation since this type of behavior cannot be explained according to the literature reviewed. Moreover, considering that k in many of the spectral components of this pattern are in the order of 6 or 7, these subsynchronous phenomena require their identification and characterization.
- [5] The results obtained from the study of this pump can be applied to another pump if the laws of geometric, kinematic and dynamic similarity among the two turbomachines are met.

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